Q.	P. (Code:	18ME0	304											R18
Re	σ	No					T	Nil (1		
ne	8 •	SIDD	HART	H INS	TITU	TE C)F EN	GINE	ERIN	G & '	L TECI	INOL) OGY:	: PUTTUI	3
		lami	its only				(AU	JTONO	OMOL	JS)	00.52				
		В.1	ech II	Year	Sem k	neste KINEI (1	r Sup MATI Mecha	oplem ICS Of mical H	entar F MA Engine	y Exa CHIN cering	amina NERY	itions	Augu	ist-2021	
Tim	e: 3	hours						<u>PAR'</u>	<u>Г-А</u>					Max. M	arks: 60
					(Ans	wer al	ll the (Questic	ons 5 x	x 2 = 1	10 Ma	rks)			
1	a	Wha	t is kutz	z back	criteri	on?									2M
	b What is the different between exact and approximate straight-line motion.											2 M			
	c	Nam	e the th	ree typ	es of	instar	taneo	us cent	ters fo	r a me	echani	sm.			2M
	d	Com	pare the	e perfo	rmanc	ce of k	cnife-e	edge, ro	oller fo	ollow	ers.				2M
	e	Wha	t is the	applica	tion o	of bev	el gea	r?							2M
								PAR'	Г-В						
					(An	swer a	all Fiv	e Units	s 5 x 1	0 = 5	0 Mar	ks)			
								UNI	T-I						
2	Ex pra	xplain actical	the inv applica	ersions ations o	of de of inve	ouble ersion	slider s.	crank	chain	with	neat	sketch	and li	st out the	10M
3	Ex pra	xplain actical	the inv	ersions ations o	of si	ingle	slider s.	crank	chain	with	neat	sketch	and li	st out the	10M
	I		TT				10	UNIT	Г-II						
4	W	ith nea	at sketcl	n, expla	ain the	e Dav	is stee	ering ge	ear of	an au	tomob	ile.			10M
								OI	R						
5	W me	ith ne echani	at sket sms.	ch, ex	plain	the	worki	ng of	any t `-III	wo c	of app	roxim	ate str	aight-line	10M
6	In	a four	bar ch	ain AB	CD, A	AD is	fixed	and is	150 r	nm lo	ng. Tl	ne crai	nk AB	is 40 mm	10M
	lor D. BA	ng and BC a AD = 6	rotates nd AD 50°	at 120 are of	r.p.n equal	n. cloo lengt	ckwis h. Fin	e, whil id the a	e the l angula	link C ir velo	D = 8 beity of	0 mm of link	oscilla CD w	ates about hen angle	
								OF	R						
7	a Define rubbing velocity at a pin joint. What will be the rubbing velocity at pin joint when the two links move in the same and opposite directions?										6M				
	b	wha Expl	t are th ain one	e vario of thei	n. n.	ethod	s used	a for f	inding	g out	accele	ration	of me	chanism?	4M
								UNII	-1 V						
8	W	hat are	the dif	ferent	ypes	of mo	otion v	vith wł	nich a	follov	ver ca	n mov	e?		10M
								Page 1	of 2						

Q.P. Code: 18ME0304

OR

R18

10M

9 A cam is to be designed for a knife-edge follower with the following data: 1. Cam lift 10M = 40 mm during 90° of cam rotation with simple harmonic motion. 2. Dwell for the next 30°. 3. During the next 60° of cam rotation, the follower returns to its original position with simple harmonic motion. 4. Dwell during the remaining 180°. Draw the profile of the cam when the line of stroke of the follower passes through the axis of the cam shaft. The radius of the base circle of the cam is 40 mm. Determine the maximum velocity and acceleration of the follower during its ascent and descent, if the cam rotates at 240 r.p.m.

UNIT-V

10	Explain	the clas	ssification	1 of	gears	with	neat	sketches.	
----	---------	----------	-------------	------	-------	------	------	-----------	--

OR

11 Explain briefly the differences between simple, compound, and epicyclic gear trains.10M What are the special advantages of epicyclic gear trains.

END